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function=newtonPoly(a,xData,x) % Returns value of Newton ' s polynomial at x. %USAGE:p=newtonPoly(a,xData,x) % a = coefficient array of the polynomial; % must be computed first by newtonCoeff. % xData = x-coordinates of data points. n = length(xData); p = a(n); for k=1:n-1; p = a(n-k) + (x - xData(n-k))^p; end.

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and hence it is a need to seek approximate solutions by means of numerical methods. Delay, differential equations (DDE) form an important class of dynamical systems. They often arise.

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Ingredients: Broken wheat: 1 cup Milk: 3 cups (pasteurised or boiled) Jaggery (traditional unrefined cane sugar)- 2 cups (or according to taste) Ghee: cup Water: 3 cups Cashews: cup Raisins (drakha or dry grapes): cup Almonds: cup Cardamom: (powdered) - tea spoon Preparation Method: Heat a frying pan on stove.

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